

## Recap

- crit. pts, reg. pts of  $f: M \rightarrow N$  smooth  
crit. value, reg. value

- corank  $\sim$  defect of  $df$  at  $x$

$$\min(m, n) - \text{rank } df_x$$

$$m \geq n \quad \text{corank} = \dim \text{coker } df_x$$

$$m \leq n \quad \text{"} = \dim \text{ker } df_x$$

- equivalence  $\Leftrightarrow$  l-r action

$$f \sim g \Leftrightarrow g = l \circ f \circ r^{-1}$$

\* stability

"every small perturbation is equiv."

- germ of a map at a point (subset)

$\rightarrow$  equivalence & stability of germs

$\downarrow$

Q: can formulate via a group-action of diffeom. germs?

Smooth maps & crit. pts  $x$

↓  
germs of maps at  $x$

↓

Jets:  $k$ -jet of  $f$  at  $x \sim$  Taylor polynomial of  $f$  at  $x$

More later, first we restrict attention to the first derivative.

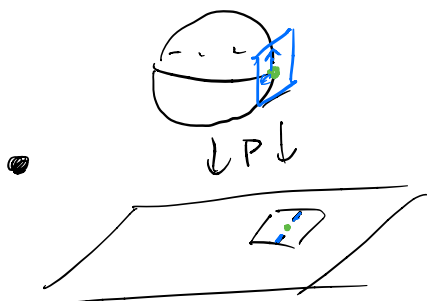
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## II. The classes $\Sigma^I$

7. Def.:  $\Sigma^i(f) = \{ x \in M \mid \text{corank}(df_x) = i \}$

Note:  $\Sigma^0(f) = \text{reg. pts.}$

e.g.



$$\{ \text{equator} \} = \Sigma^1(p)$$

$$S^2, \{ \text{eq.} \} = \Sigma^0(p)$$

- $f(z) = z^2$  as smooth map

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x^2 - y^2 \\ 2xy \end{pmatrix} \quad df_{f(x,y)} = \begin{pmatrix} 2x & -2y \\ 2y & 2x \end{pmatrix}$$

$$\Rightarrow \begin{aligned} \Sigma^2(f) &= \{0\} \\ \Sigma^1(f) &= \emptyset \end{aligned} \quad \Sigma^0(f) = \mathbb{R}^2 - \{0\}$$

Q: stable?

$\rightsquigarrow$  Do the  $\Sigma^i(f)$  give us a decomposition of  $M$ ?

§.Thm.: For a "generic" map  $f: M \rightarrow N$

the sets  $\Sigma^i(f)$  are submanifolds of  $M$  with

$$\text{codim } \Sigma^i(f) := \dim M - \dim \Sigma^i(f)$$

$$= i \cdot \left( \underbrace{|\dim N - \dim M| + i}_{\text{"corank at the target"}}$$

$$= \begin{matrix} \uparrow \\ \text{corank} \\ \text{of } f \end{matrix} (\dim M - r) \cdot (\dim N - r) \quad \text{w. } r = \text{rank } df$$

(if this nr. is neg., then  $\Sigma^i(f) = \emptyset$ ).

We put this theorem to use by simple dimension-counts:

→  $z \mapsto z^2$  is generic as holomorphic map,  
but not as a smooth map.

→ generic smooth maps from  $\mathbb{R}^m \rightarrow \mathbb{R}^n$   
have  $\Sigma^m(f) = \emptyset$ , more generally

$$\Sigma^i(f) = m - i^2$$

To prove the theorem we look first at the linear

Case:

Consider  $\mathcal{L}_{mn} := \text{Hom}(\mathbb{R}^m, \mathbb{R}^n) \cong \{A \in M_{n,m}(\mathbb{R})\} \cong \mathbb{R}^{m \cdot n}$

left-right action of  $GL_m \times GL_n$  on  $\mathcal{L}_{mn}$  (drop the " $\mathbb{R}$ ")

$\forall A \in M_{nm} \quad \exists R \in GL_m, L \in GL_n$

s.t.  $LA R^{-1} = A_0 := \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}$

where  $r = \text{rank}(A)$

9. Lemma The set of all matrices of rank  $r$   
 $M_{n,m}^r = \{ A \in M_{n,m} \mid \text{rank}(A) = r \} \subset M_{n,m}$  is  
 a submanifold with  $\text{codim } M_{n,m}^r = (m-r) \cdot (n-r)$   
 $= i(n-m+i)$

Proof

Fix  $r$  and let  $A \in M_{n,m}^r$ . After changing  
 coordinates we can assume

$$A = \begin{matrix} & \begin{matrix} r & m-r \end{matrix} \\ \begin{matrix} r \\ n-r \end{matrix} & \begin{pmatrix} B & C \\ \vdots & \vdots \\ D & E \end{pmatrix} \end{matrix} \begin{matrix} r \\ n-r \end{matrix} \quad \text{with } B \in GL_r$$

right-multiply by  $\begin{pmatrix} I_r & -B^{-1}C \\ 0 & I_{n-r} \end{pmatrix}$  gives

$$\begin{pmatrix} B & 0 \\ 0 & E - DB^{-1}C \end{pmatrix} \quad \text{which has rank } r$$

$$\Leftrightarrow E = DB^{-1}C \in M_{n-r, m-r}$$

Now define  $F: M_{n,m} \rightarrow M_{n-r,m-r}$

$$A = \begin{pmatrix} B & C \\ D & E \end{pmatrix} \mapsto E - DB^{-1}C$$

and observe

- $F$  smooth
- $0 \in M_{n-r,m-r}$  is a reg. value

$$\left[ \begin{array}{l} \text{for } X \in M_{n-r,m-r} \\ \text{consider } \gamma(t) = \begin{pmatrix} B & C \\ D & E+t \cdot X \end{pmatrix} \\ \gamma(0) \xrightarrow{dF} X \end{array} \right]$$

preimage then

$$\implies F^{-1}(0) = M_{nm}^r \text{ is a submf}$$

$$\text{of } M_{nm} \text{ of codim } M_{nm}^r = \dim M_{n-r,m-r} \\ = (n-r)(m-r)$$



Our goal: Lift Lemma 9 to Theorem 8.

For this we need the notion of

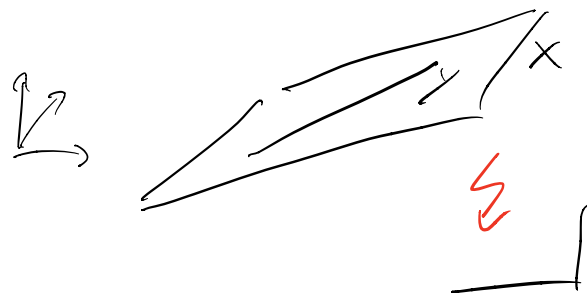
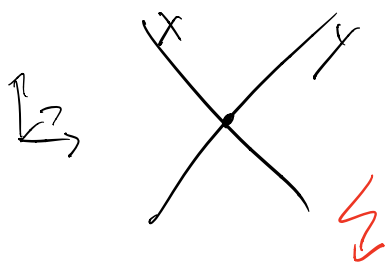
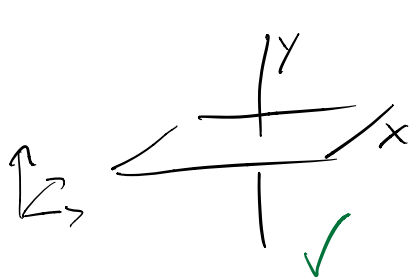
transversality ("opposite of tangency")

## 10. Def.:

1.  $V$  vect. space,  $X, Y$  lin. subspaces are called **transversal** (in  $V$ ),  $X \pitchfork Y$ , if

$$V = X + Y \quad (\text{or } X \cap Y = \phi)$$

e.g.:



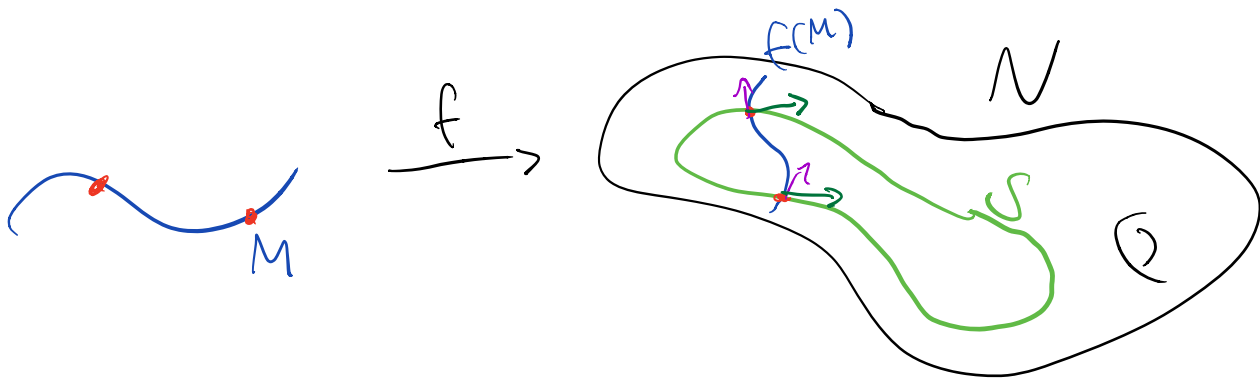
2.  $f: M \rightarrow N$  smooth,  $S \subset N$  submf.

$f$  is transversal to  $S$  at  $x \in M$

if either  $f(x) \notin S$

$$\text{or } df_x(T_x M) + T_{f(x)} S = T_{f(x)} N$$

$f$  is transversal to  $S$ ,  $f \pitchfork S$ , if this holds for all  $x \in M$ .



II. Prop.:

If  $f \pitchfork S$ , then  $f^{-1}(S)$  is a submanifold of  $M$  with  $\text{codim } f^{-1}(S) = \text{codim } S$ .

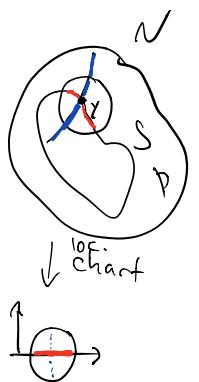
Proof: Find  $F: M \rightarrow \mathbb{R}^{n-k}$  ( $k = \dim S$ ) with  $F^{-1}(0) = f^{-1}(S)$  and use preimage theorem.

Let  $y \in S$ .  $S$  submanifold  $\Rightarrow$  locally there are coordinates

$(y_1, \dots, y_k, y_{k+1}, \dots, y_n)$  s.t.  $S = \underline{(y_1, \dots, y_k, 0)}$   $\in \mathbb{R}^{n-k}$

Define  $g: N \rightarrow \mathbb{R}^{n-k}$ ,  $(y_1, \dots, y_n) \mapsto (y_{k+1}, \dots, y_n)$

Then  $g$  is smooth with  $S = g^{-1}(0)$





and  $dg_{(y_1, \dots, y_n)}$  surjective.

preimage then

$$\Rightarrow \ker dg_x = T_x S,$$

Define  $F = g \circ f : M \rightarrow \mathbb{R}^{n-k}$ . Then  $F$  is

smooth,  $F^{-1}(0) = f^{-1}(S)$  and  $DF_x$  is surjective

for all  $x \in f^{-1}(S)$  by transversality:

$$f \pitchfork S : \quad df_x(T_x M) + T_{f(x)} S = T_{f(x)} N$$

||  
ker  $dg_{f(x)}$ !

"apply"  $dg_{f(x)}$  to get

$$\begin{aligned} dg_{f(x)} df_x(T_x M) + dg_{f(x)}(\ker dg_{f(x)}) \\ \parallel \\ dF_x(T_x M) &= dg_{f(x)}(T_{f(x)} N) \\ &= \mathbb{R}^{n-k} \end{aligned}$$



We're getting closer to an idea of the term "generic" ...

12 Thm: (weak transversality theorem)

For  $M$  closed,  $S \subset N$  closed, the set of maps transversal to  $S$ ,

$$C_{\neq S}^{\infty}(M, N) = \{ f \in \underline{C^{\infty}(M, N)} \mid f \pitchfork S \}$$

forms an open dense set in  $C^{\infty}(M, N)$ , both in the weak and strong topology.

Roughly:

$$\text{strong} \sim U_{\varepsilon}(f) = \left\{ g \in C^{\infty}(M, N) \mid \left. \begin{array}{l} \|D^k f - D^k g\|_{\infty} < \varepsilon \\ \text{for all } k \in \mathbb{N} \end{array} \right\} \right.$$

weak  $\sim$  same but condition reduced to hold for compact sets only.

More on these topologies later (or see the book "Differential Topology" by Hirsch)

